

es-stable-2^{0,22}

$\forall es:ES, i, x, y:Id, Tx, Ty:Type, P:(Tx \rightarrow Ty \rightarrow Prop), Lx, Ly:Knd\ List.$

$es\text{-frame}(es;i;Lx;x;Tx)$

$\Rightarrow es\text{-frame}(es;i;Ly;y;Ty)$

$\Rightarrow \forall e@i. (\text{kind}(e) \in Lx @ Ly) \Rightarrow P(x \text{ when } e, y \text{ when } e) \Rightarrow P((x \text{ after } e), (y \text{ after } e))$

$\Rightarrow @i \text{ stable } state.P(state.x, state.y)$